



High-resolution imaging systems for high-speed railway inspection



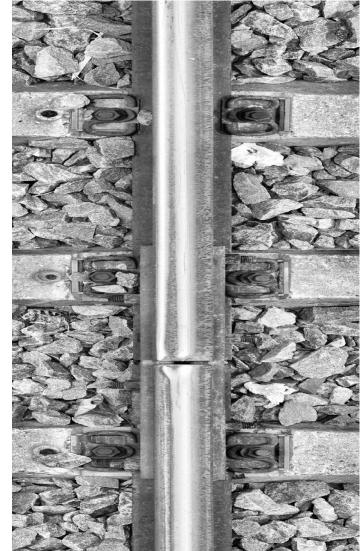


HRS is a high-resolution imaging system designed for detailed inspection of railway surfaces.

It uses high-definition cameras to capture submillimeter images at high speed, making it ideal for analyzing rails, fasteners, sleepers, slabs and other components.

Mountable on virtually any vehicle and orientable toward the target, HRS ensures precise acquisition even at full speed, thanks to its proprietary lighting and synchronization system with microsecond-level accuracy.



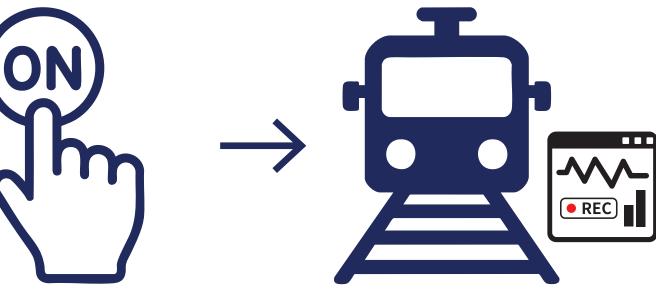


| Performance | |
|-----------------|-----------------------------|
| Resolution | Up to 0,05 mm/px |
| Image Type | Color (RGB) or Mono |
| Max Speed | Up to max operational speed |
| Target distance | Up to 1000 mm |
| Operating temp. | -20°C / + 50°C |
| Humidity | 15 to 85% |
| Lighting Power | 100.000 Lux |
| Voltage | 24 VDC or 220-110 VAC |

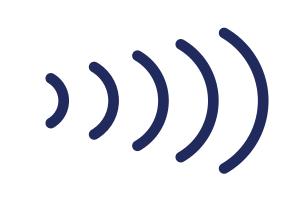
How it works



System Startup: The HRS system is activated.



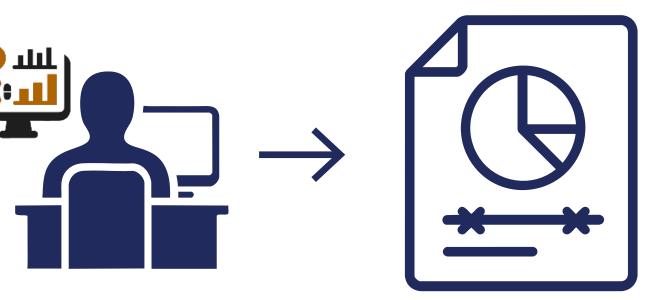
Data Acquisition:
Scanning begins via
Gilgamesh software
and onboard sensors.



Acquired data is transferred to office servers.

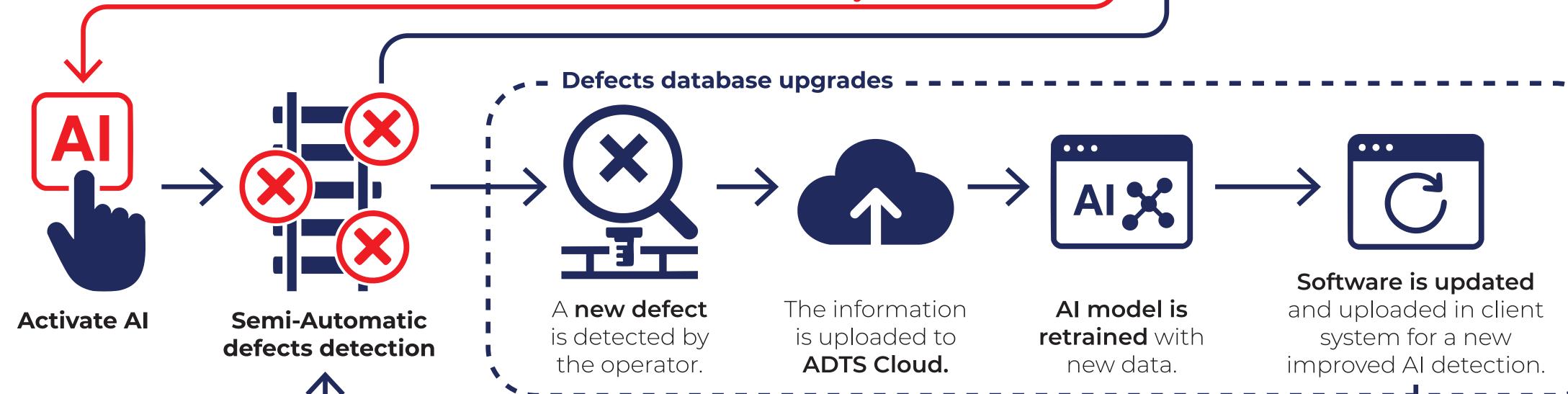


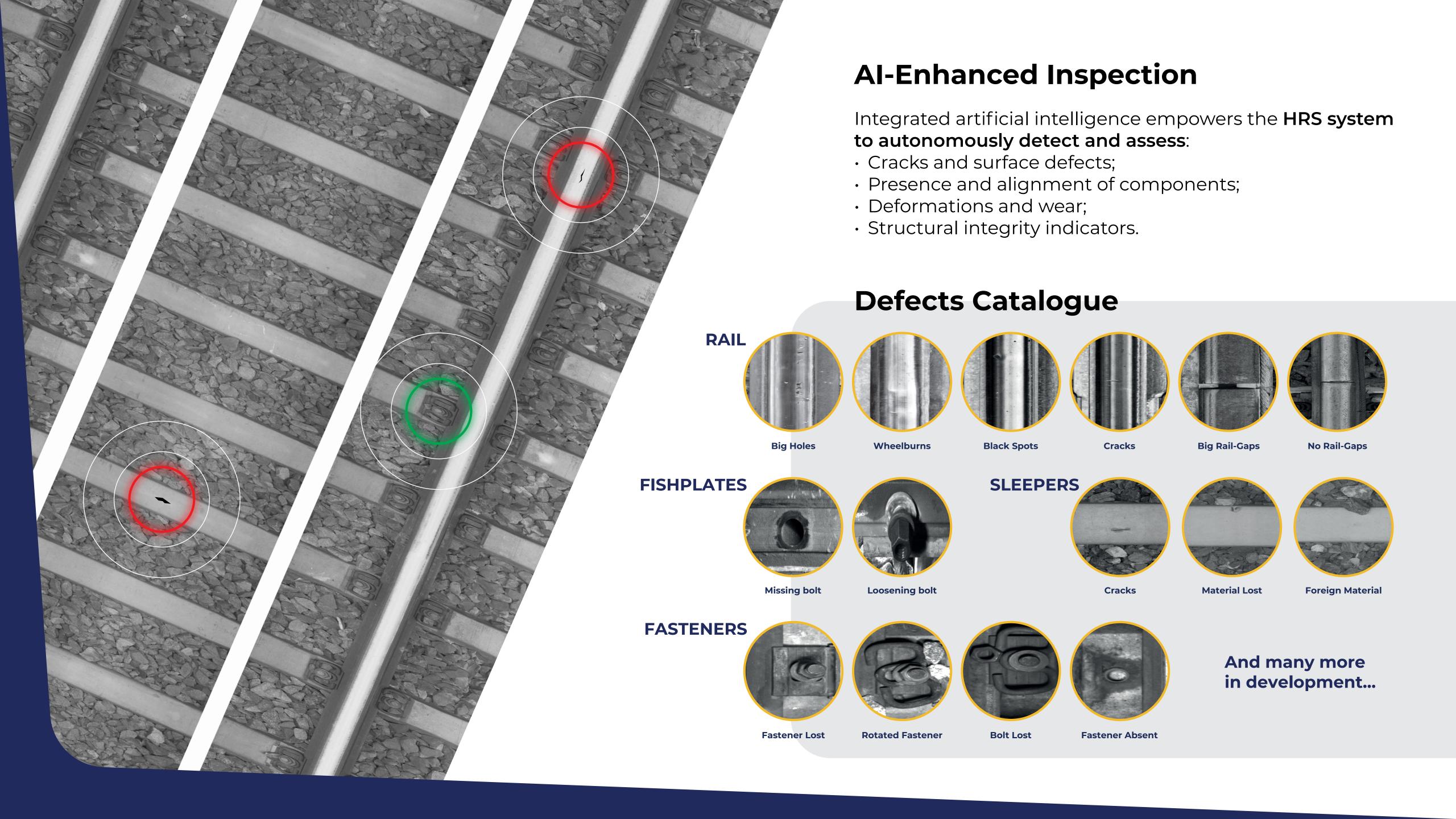
Data Analysis: Ahmes software processes the information.



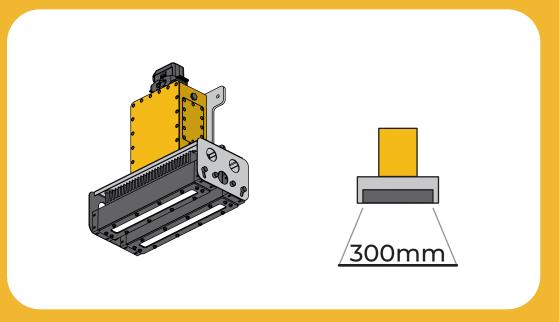
Report Generation:
Results are compiled into structured, web-accessible reports.

the AI semi-automatically identifies defects





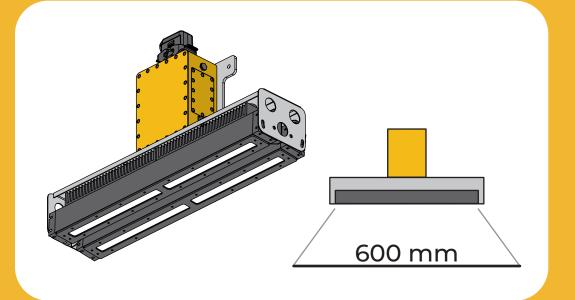
Models and Configurations



HRS

High-resolution imaging for targeted rail inspection

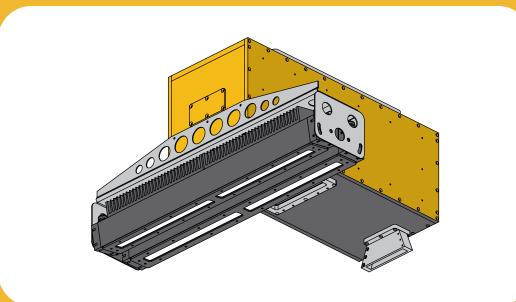
| Resolution | 0,05 mm/px |
|------------|------------|
| FOV | 300 mm |



HRSW

Full-track coverage with multiple synchronized units.

| Resolution | 0,1 mm/px |
|------------|-----------|
| FOV | 600 mm |



V3DS

Integrates laser triangulation for enhanced 3D imaging

| Resolution | 0,1 mm/px |
|------------|-----------|
| FOV | 600 mm |

Rail Surface Configuration



Devices:

• 2 x HRS

Defects detection:

Rail

Rail View Configuration



Devices:

• 2 x HRSW

Defects detection:

- Rail
- Fasteners

Side Rail Configuration









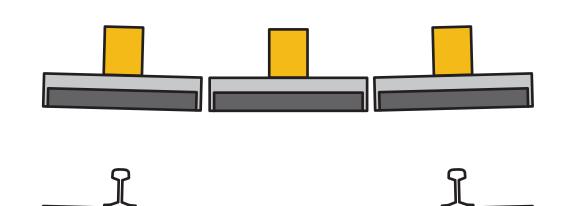
Devices:

• 4 x HRS

Defects detection:

Fishplates

Full Track Configuration



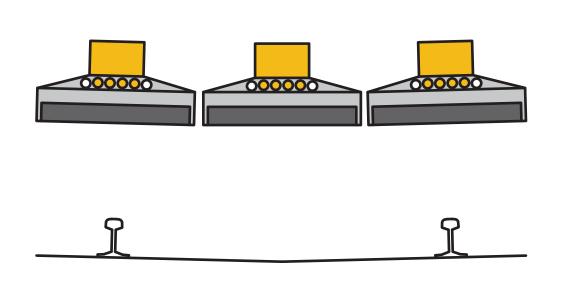
Devices:

• 3 x HRSW

Defects detection:

- Rail
- Fasteners
- Sleepers

3D Full Track Configuration



Devices:

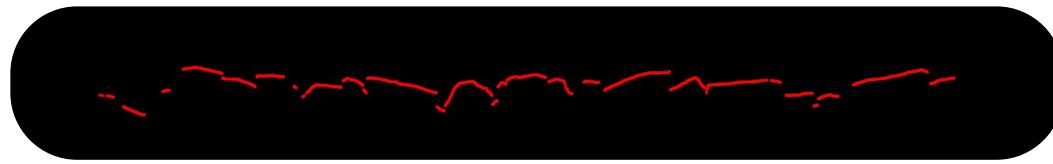
• 3 x V3DS

Defects detection:

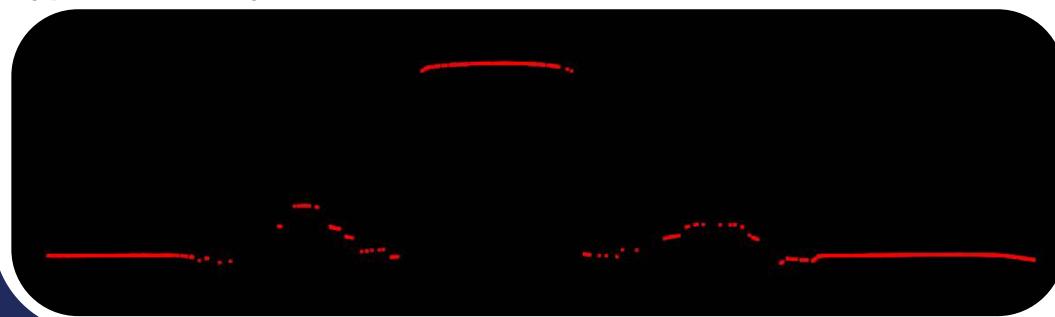
- Rail
- Fasteners
- Sleepers
- Ballast

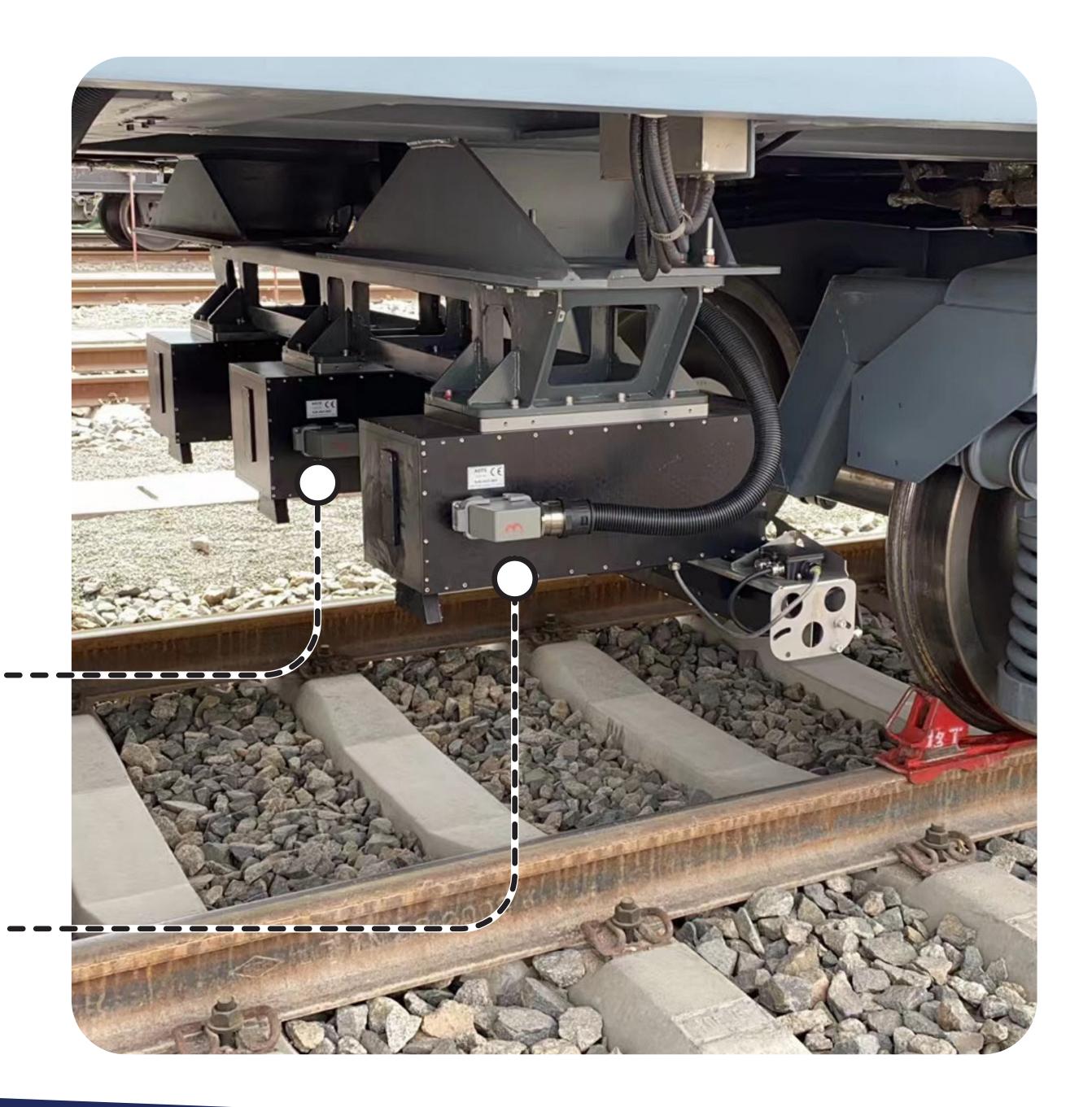
The Track Surface configuration with three V3DS units enables the simultaneous acquisition of the railway track's 3D shape and high-resolution images, which are then correlated through dedicated analysis software.

Typical Ballast Profile



Typical Railway Profile







Acquisition and Review

Proprietary software allows data to be collected and analyzed either directly from the vehicle's control cabin or remotely from a separate location.



